

Applying Traffic Engineering Tools to Resource Road Safety



FPInnovations Webinar

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Responding to members' needs



BC Forests, Lands, Natural Resource Operations & Rural Development, industrial resource road operators

NEED:

Systematic and objective methodology to assess safety of resource roads



Road: quantification of safety

Vehicles: assess safe traffic capacity

Traffic Engineering

Traffic engineering components



Vehicle Data

- Collection methods
- Safety analysis
 - Now/future **safe capacity**
- Traffic mitigation methods



Road Data

- Collection methods
- Analysis methods
- Cost issues
- Refinement of collection, analysis, and reporting

Overview of presentation

Theory:

- Need for field data collection, traffic microsimulation

Traffic data:

- Tools used, costs, limitations, post-processing

Microsimulation:

- How traffic field data fits, workflow, possible analyses

Conclusions:

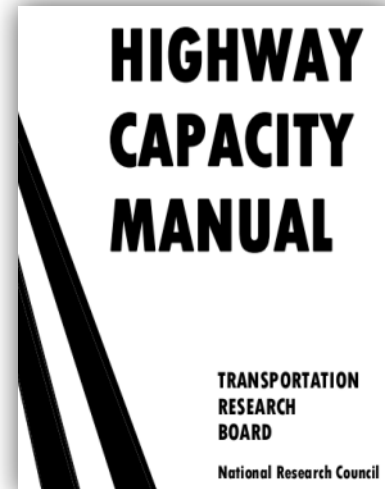
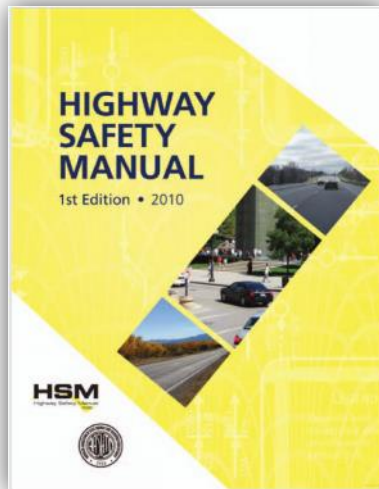
- Benefits , questions, your insights, conversation

Theory: related fields

Calibrating your
crash data to crash
data database

“Safe Capacity”

“Level of service”
based on measures of
effectiveness

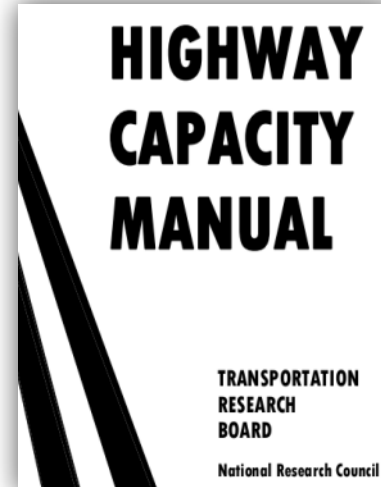
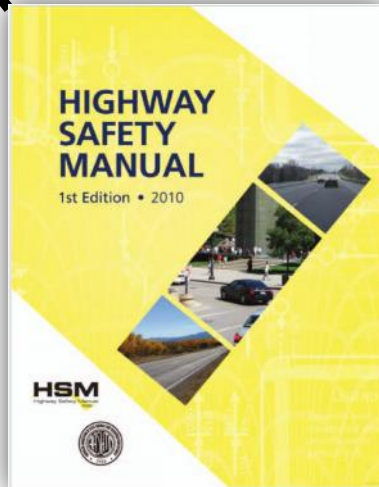


Theory: related fields

Requires crash data for
CMFs and SPFs (not
available)

“Safe Capacity”
of resource roads

Does not have any
directly applicable
solutions

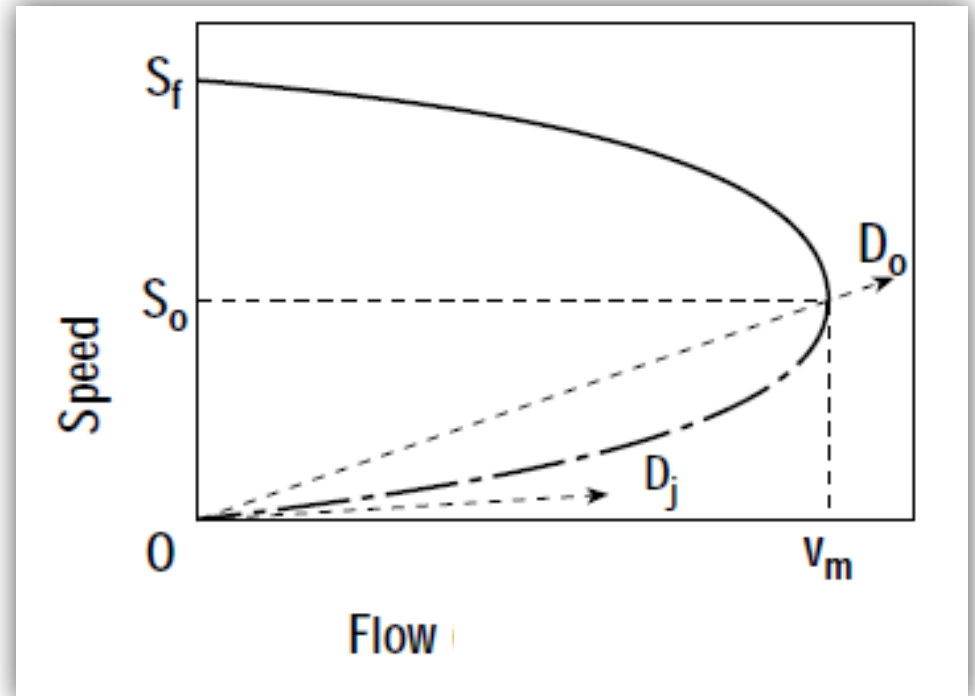


Better safety \neq Better level of service

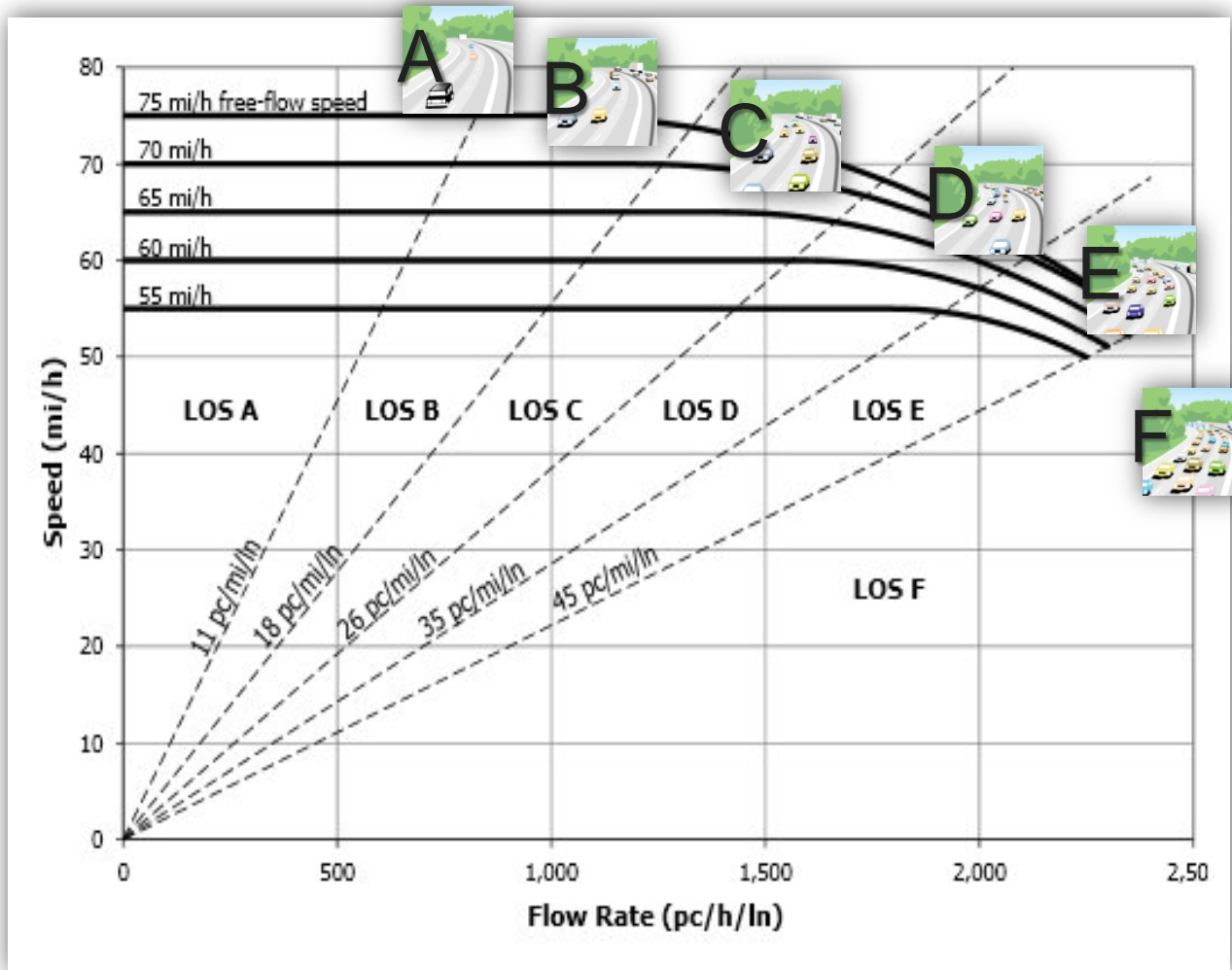
Theory: capacity

Capacity: hard to measure directly

Capacity analysis: considers a “prescribed” level of operation



Theory: level of service – multilane highway

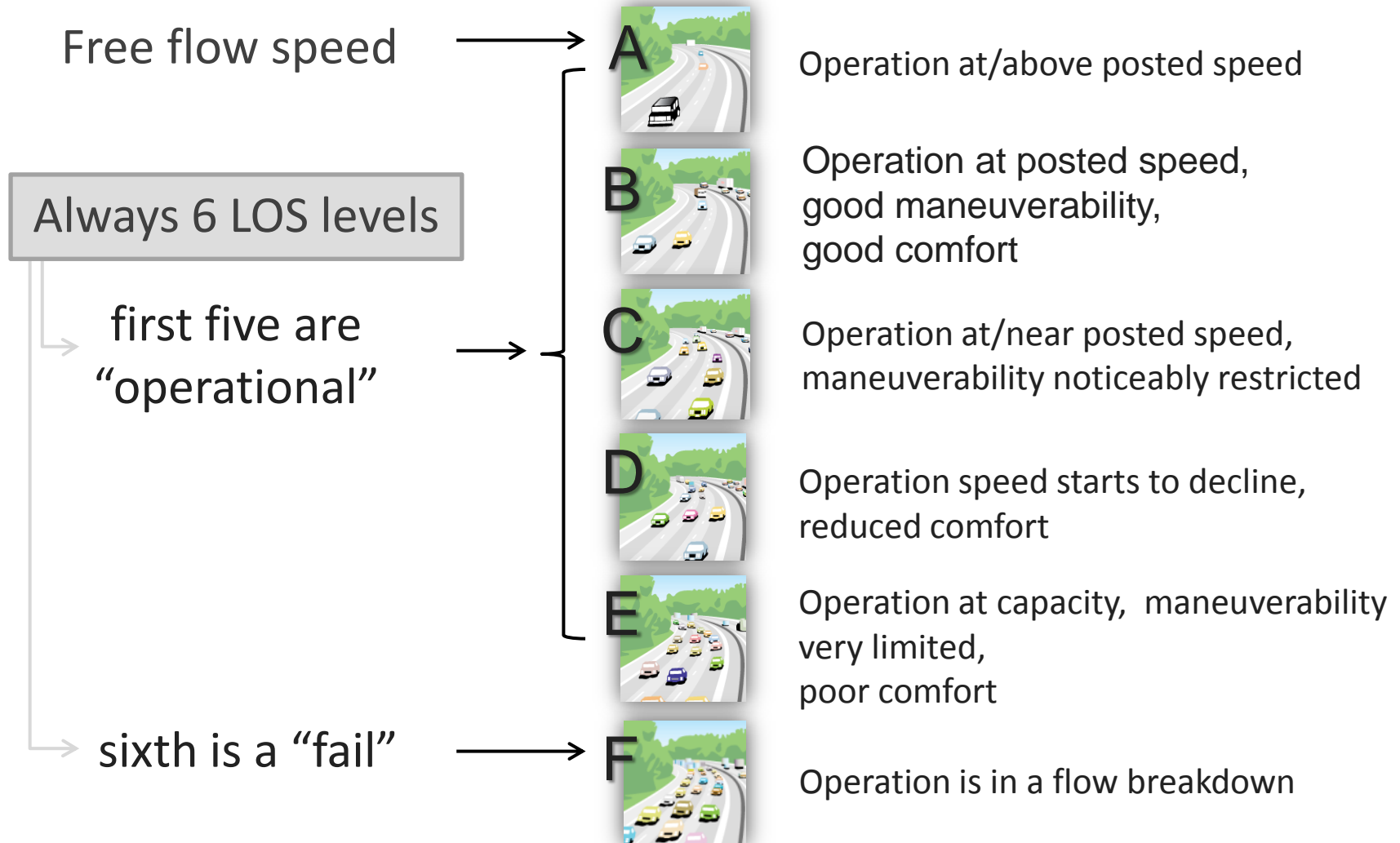


LOS: “[quantitative] quality measure describing operational conditions within a traffic stream, generally in terms of such service measures as:

- speed/travel time
- Freedom to maneuver
- Traffic interruptions
- Comfort and convenience”

- HCM

Theory: LOS – multilane highway



Images from:: http://www.mdt.maryland.gov/I95section100DELETE/I95-sect100_los.html

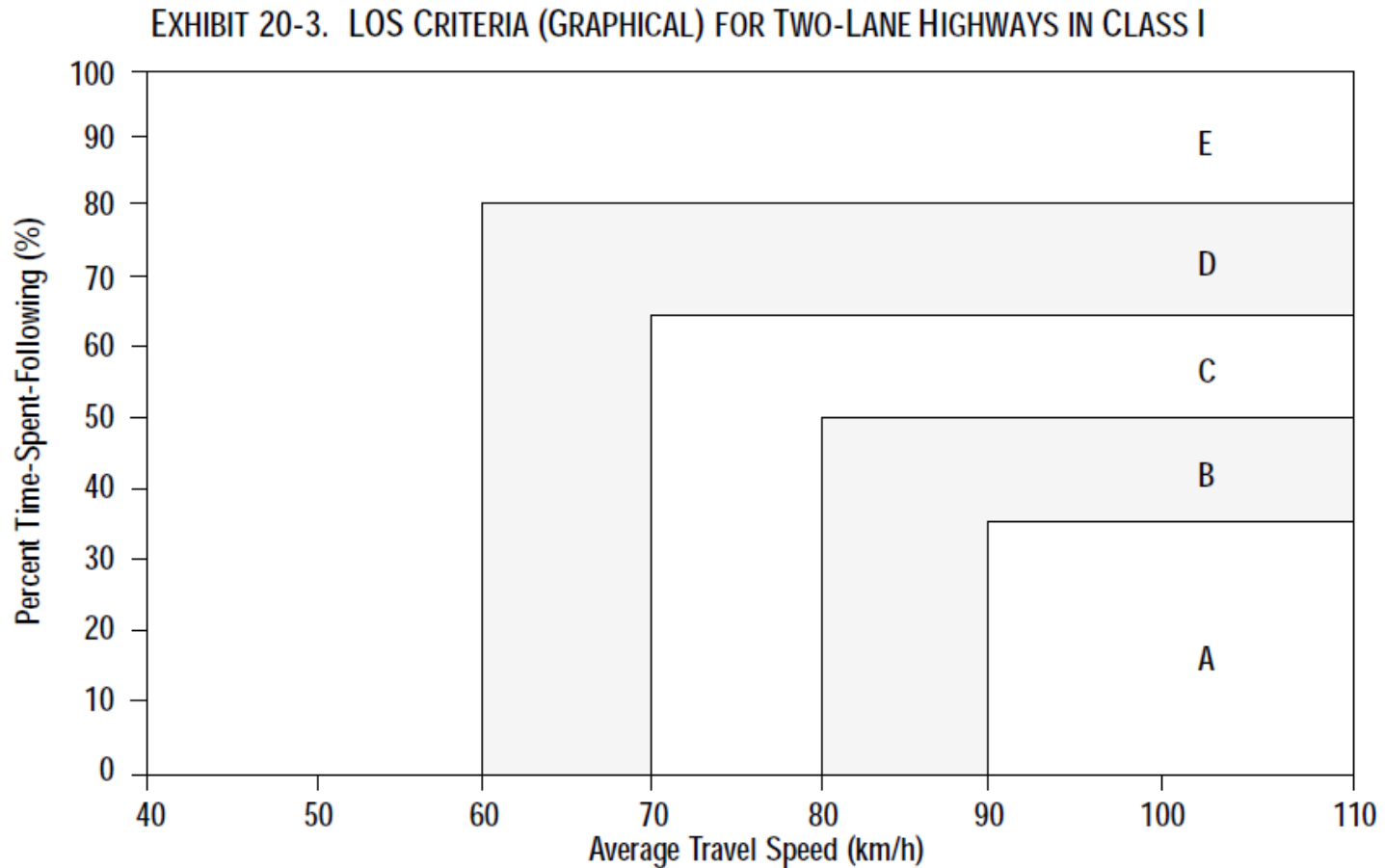
Theory: measures of effectiveness

- MOE metrics used by LOS
- MOE: many kinds
- Different MOE for various infrastructure

	Speed	Density	PTSF	Delay
Multilane Highway	X	X		
Two Lane Highway	X		X	
Urban street	X			
Intersection				X

PTSF = percent time spent following

Theory: LOS – two-lane highway



Theory: LOS – two-lane highway

EXHIBIT 12-5. EXAMPLE SERVICE VOLUMES FOR MULTILANE HIGHWAYS
(SEE FOOTNOTE FOR ASSUMED VALUES)

FFS (km/h)	Number of Lanes	Terrain	Service Volumes (veh/h)				
			A	B	C	D	E
100	2	Level	1200	1880	2700	3450	4060
		Rolling	1140	1800	2570	3290	3870
		Mountainous	1040	1640	2350	3010	3540
	3	Level	1800	2830	4050	5180	6100
		Rolling	1710	2700	3860	4940	5810
		Mountainous	1570	2470	3530	4520	5320
80	2	Level	960	1510	2190	2920	3520
		Rolling	910	1440	2090	2790	3360
		Mountainous	830	1310	1910	2550	3070
	3	Level	1440	2260	3290	4390	5290
		Rolling	1370	2160	3140	4180	5040
		Mountainous	1250	1970	2870	3830	4610

Notes:

Assumptions: highway with 100-km/h FFS has 5 access points/km; highway with 80-km/h FFS has 15 access points/km; lane width = 3.6 m; shoulder width > 1.8 m; divided highway; PHF = 0.88; 5 percent trucks; and regular commuters.

Theory: LOS – interrupted flow

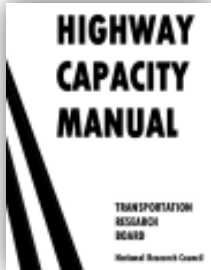
EXHIBIT 15-2. URBAN STREET LOS BY CLASS

Urban Street Class	I	II	III	IV
Range of free-flow speeds (FFS)	90 to 70 km/h	70 to 55 km/h	55 to 50 km/h	55 to 40 km/h
Typical FFS	80 km/h	65 km/h	55 km/h	45 km/h
LOS	Average Travel Speed (km/h)			
A	> 72	> 59	> 50	> 41
B	> 56–72	> 48–59	> 40–50	> 32–41
C	> 40–56	> 32–48	> 24–40	> 23–32
D	> 32–40	> 24–32	> 16–24	> 18–23
E	> 26–32	> 16–24	> 12–16	> 14–18
F	≤ 26	≤ 16	≤ 12	≤ 14

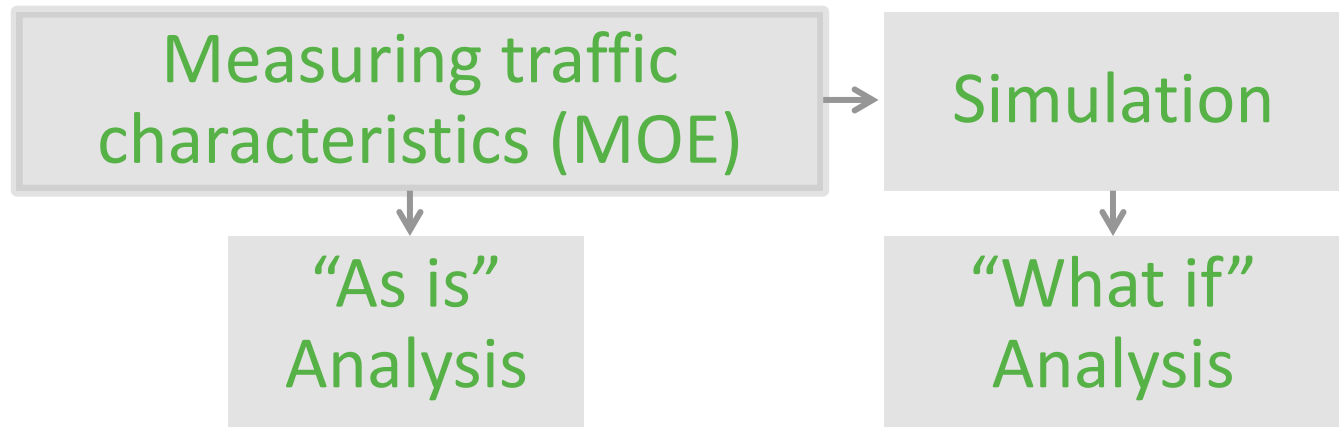
SIGNAL DENSITY BY URBAN STREET CLASS

Urban Street Class	Default (signals/km)
I	0.5
II	2
III	4
IV	6

Theory: what about a resource road?

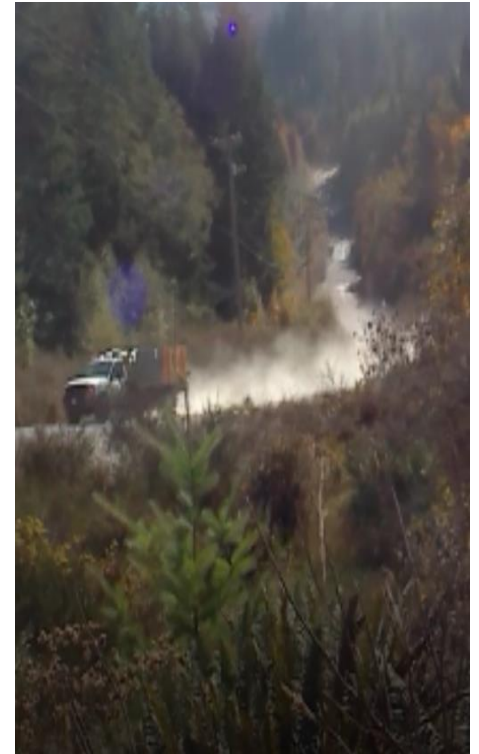


- Does not deal with weather, large grades, passing lanes, narrow bridges...
- Points to traffic simulation for more complex situations



Theory: traffic metrics related to safety

- Roads with radio-controlled one lane sections:
 - Number of pullout occurrences
 - Total time spent stopped at pullouts (delay)
 - Number of pullout overcrowding events
- General metrics for any road:
 - Percent time spent following
 - Number of passing occurrences
 - Average speed and variance
 - Vehicle type classification
 - Average traffic volumes per hour



How to get all this data... economically?

Traffic data: magnetic counters



- Relatively inexpensive (\$400)
- TrafX is industry standard
- Not always reliable

- Count



≡ TRAFx

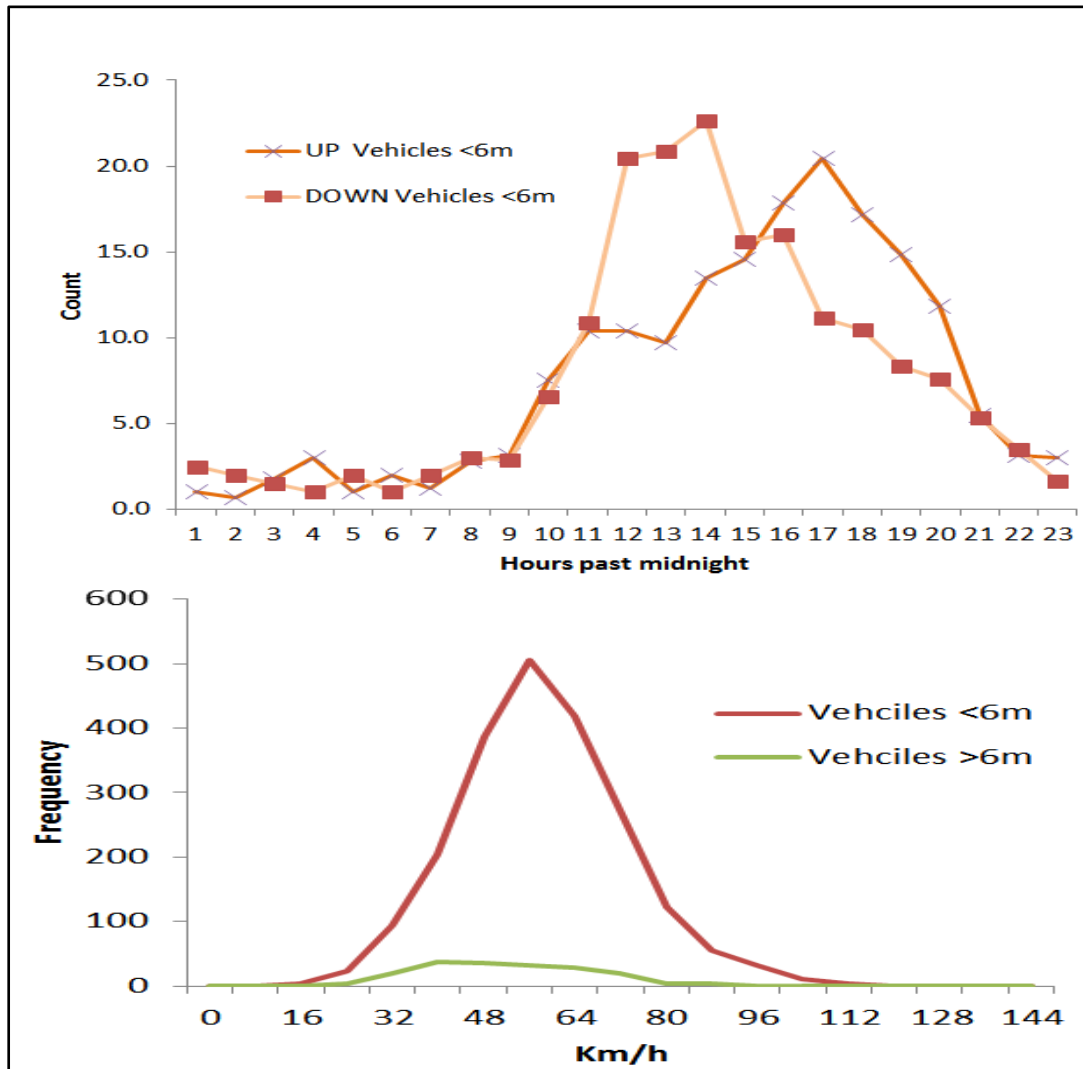
Traffic data: radar

- On straight part of road, facing particular angle, clear shot
- \$5000 +



- Spot speed
- Direction
- Vehicle length

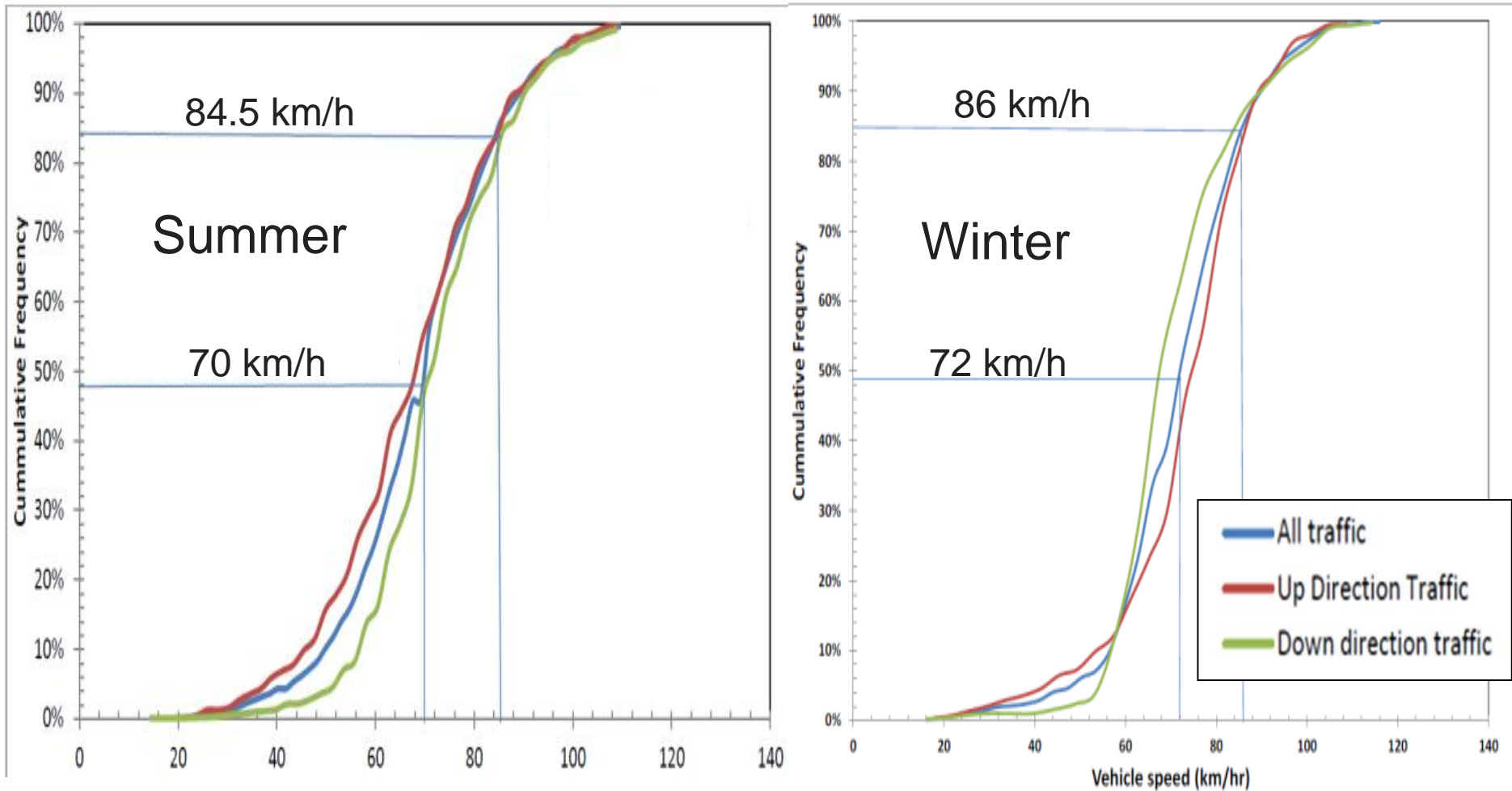
Traffic data: radar post-processing



Insights:

- Traffic flow patterns over time of day
- Distribution of spot speed for vehicle length categories
- Headway distribution/ percent vehicle following (1 second time resolution)
- ...

Traffic data: radar post-processing



Traffic data: motion cameras



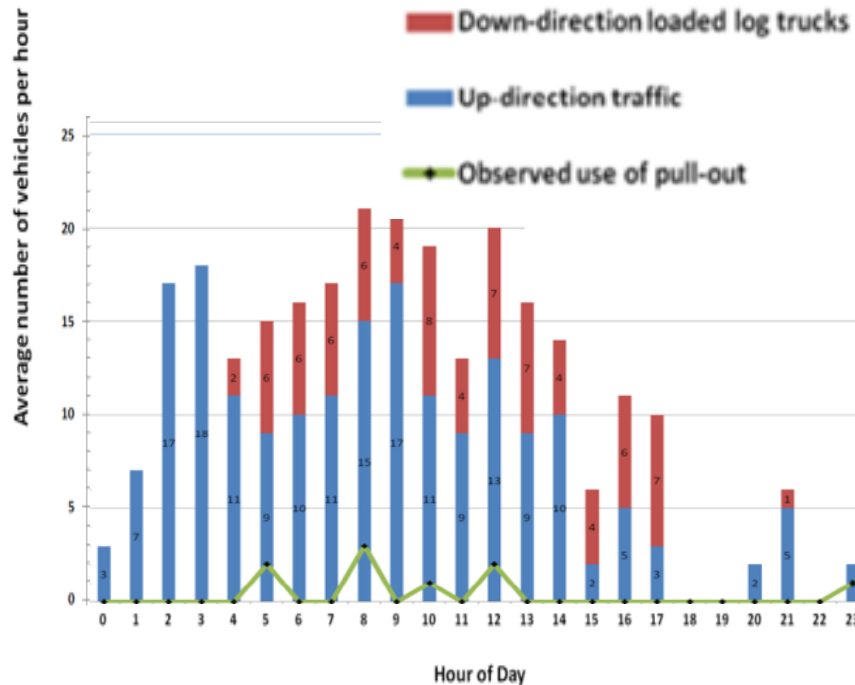
- Tested four motion cameras (\$150 - \$700):
 - produced timekeeping
 - unreliable in capturing fast vehicles or vehicles that are following other



Traffic data: motion cameras post-processing

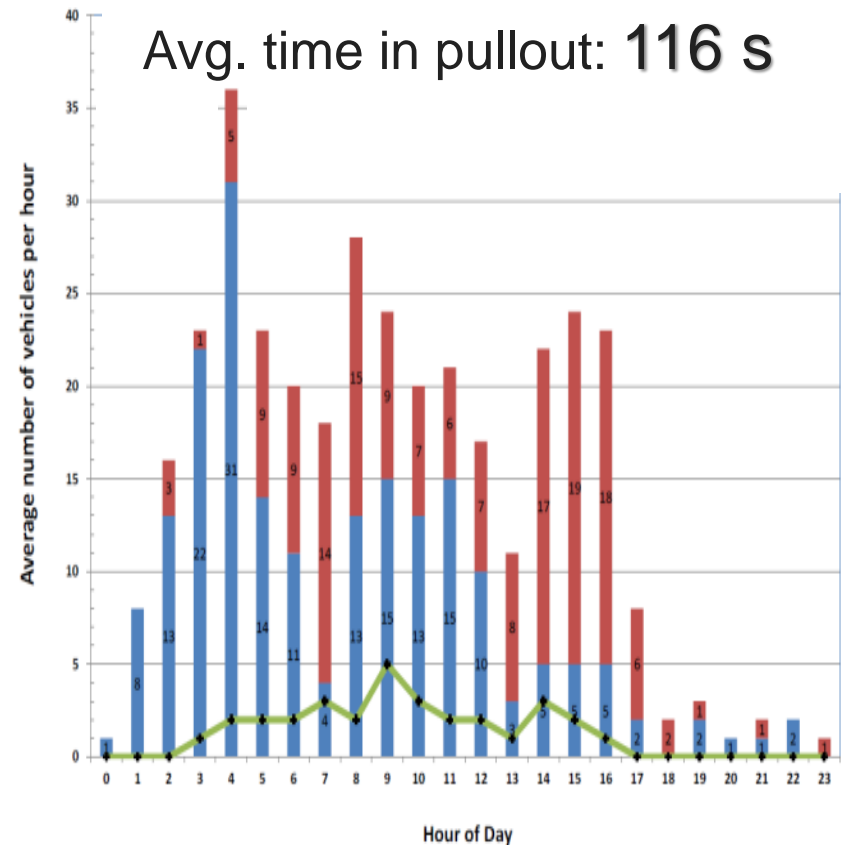
Summer

Avg. time in pullout: **74 s**



Winter

Avg. time in pullout: **116 s**



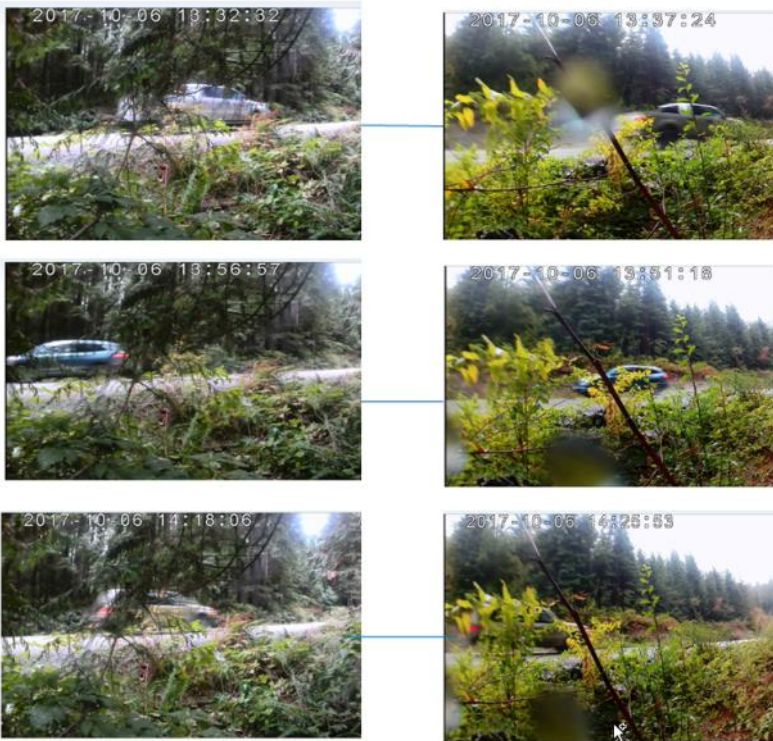
Traffic data: video cameras

- Camera + SD card + waterproofing + battery (as low as \$300)

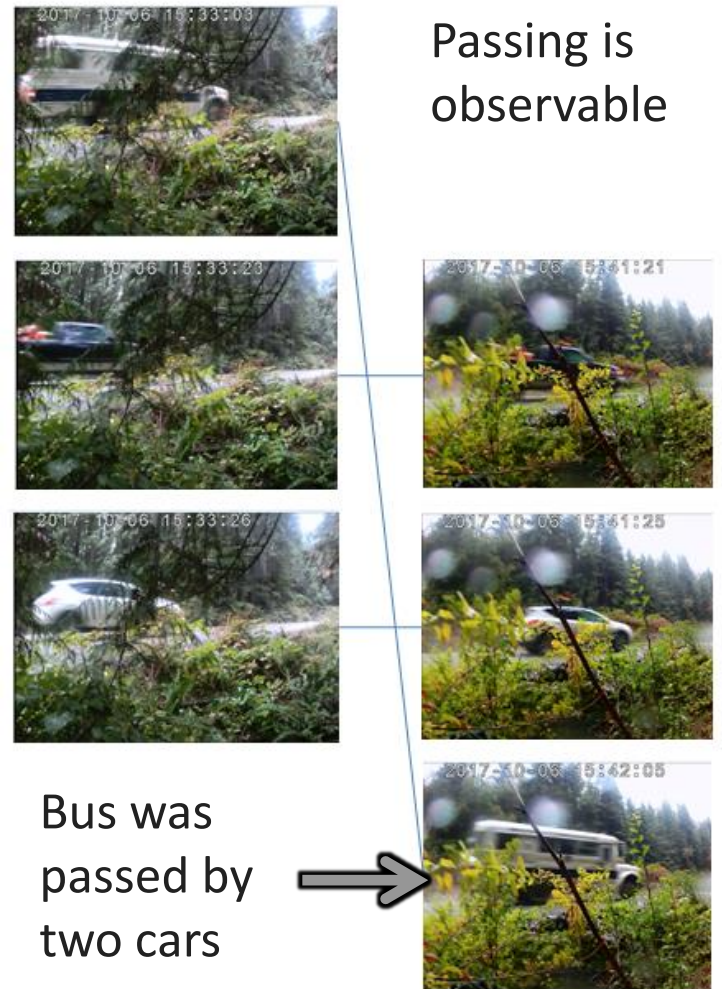


- Capture all traffic reliably with relatively little time drift

Traffic data: video post-processing



Speeds for types of vehicle over a road segment



Passing is observable

Bus was passed by two cars

Traffic data: video post-processing



Traffic data: video post-processing



Traffic data: video post-processing



Traffic data: video post-processing

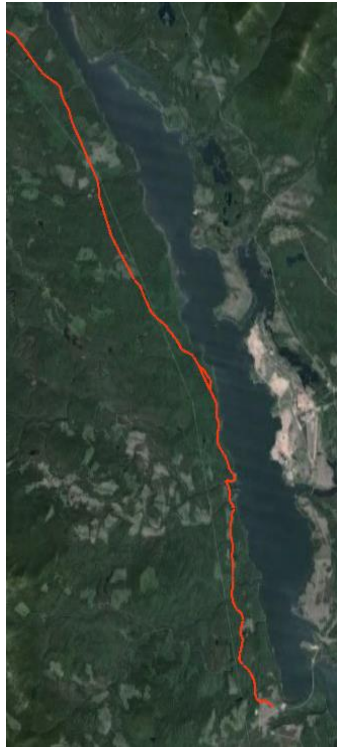


Traffic data: video post-processing



Microsimulation: data collection needs

Finlay FSR (60KM)



Interior BC

Industrial traffic

One lane sections

Florence FSR (8KM)

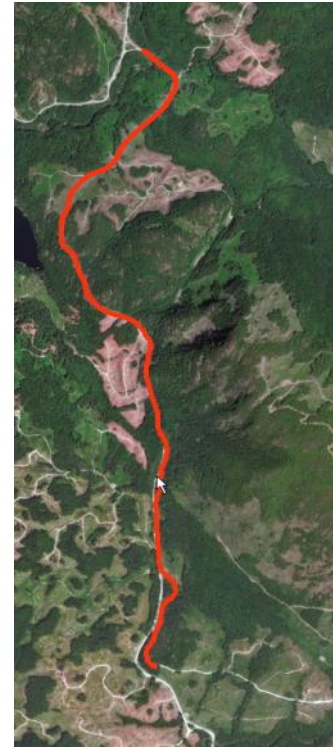


Coastal BC

Recreational traffic

Four one lane bridges

Bamfield Main (7KM)



Coastal BC

Mixed traffic

One lane section

Various tools:

- Roadside sensors
- GPS mapping
- Interviews
- GPS on trucks

Left out ~ 1 week

Need input and
validation data

Microsimulation: definition

“[Traffic] Microsimulation models are dynamic, stochastic, discrete time modelling techniques that simulate the movement of individual vehicles based on car-following, lane changing and gap acceptance algorithms that are updated several times every seconds. These vehicle-to-vehicle interactions provide the basis for calculating delays”

– Traffic Modeling Guidelines, Transport Roads & Maritime Services (2013)

Microsimulation: process

1. Verification:

- Making sure there are no logic errors in the model (using general observation/knowledge)

2. Calibration:

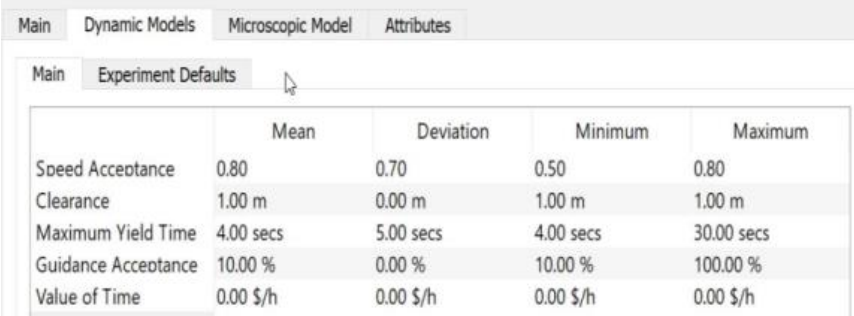
- Iterating model parameters so that output variable matches the *field observations*

3. Validation:

- Use *field data* that was not used during calibration as a final check of road model

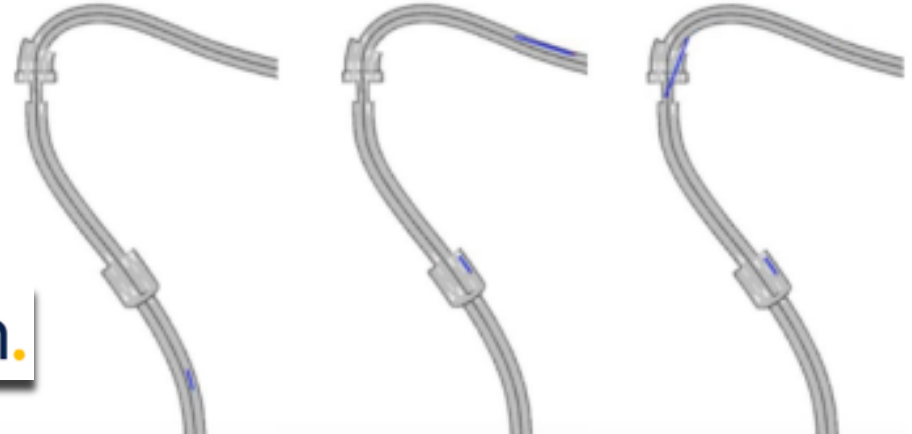
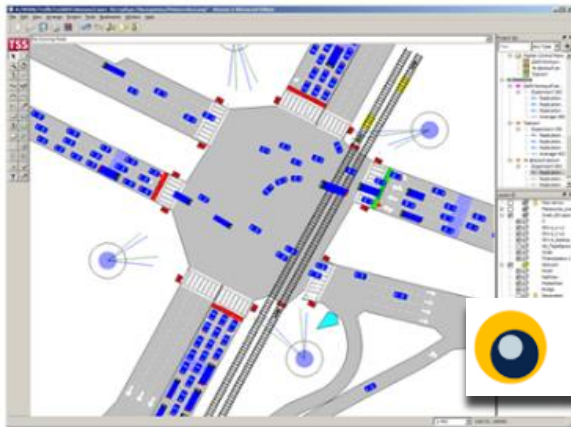
4. Output:

- Run many simulations to create average and variance for metrics of interest



	Mean	Deviation	Minimum	Maximum
Speed Acceptance	0.80	0.70	0.50	0.80
Clearance	1.00 m	0.00 m	1.00 m	1.00 m
Maximum Yield Time	4.00 secs	5.00 secs	4.00 secs	30.00 secs
Guidance Acceptance	10.00 %	0.00 %	10.00 %	100.00 %
Value of Time	0.00 \$/h	0.00 \$/h	0.00 \$/h	0.00 \$/h

Microsimulation: tool developed




API was developed to accommodate radio pullout use

- pullout rules / conditions
- radio calls – supports % without radios
- slowing down/pulling over for loaded vehicles
- counting statistics unique to resource roads
- defining behaviors of various vehicles
- scripts that automate building Aimsun models


Microsimulation: entire workflow

Traffic data and
Field mapping



 Cleaning/preparing
all data



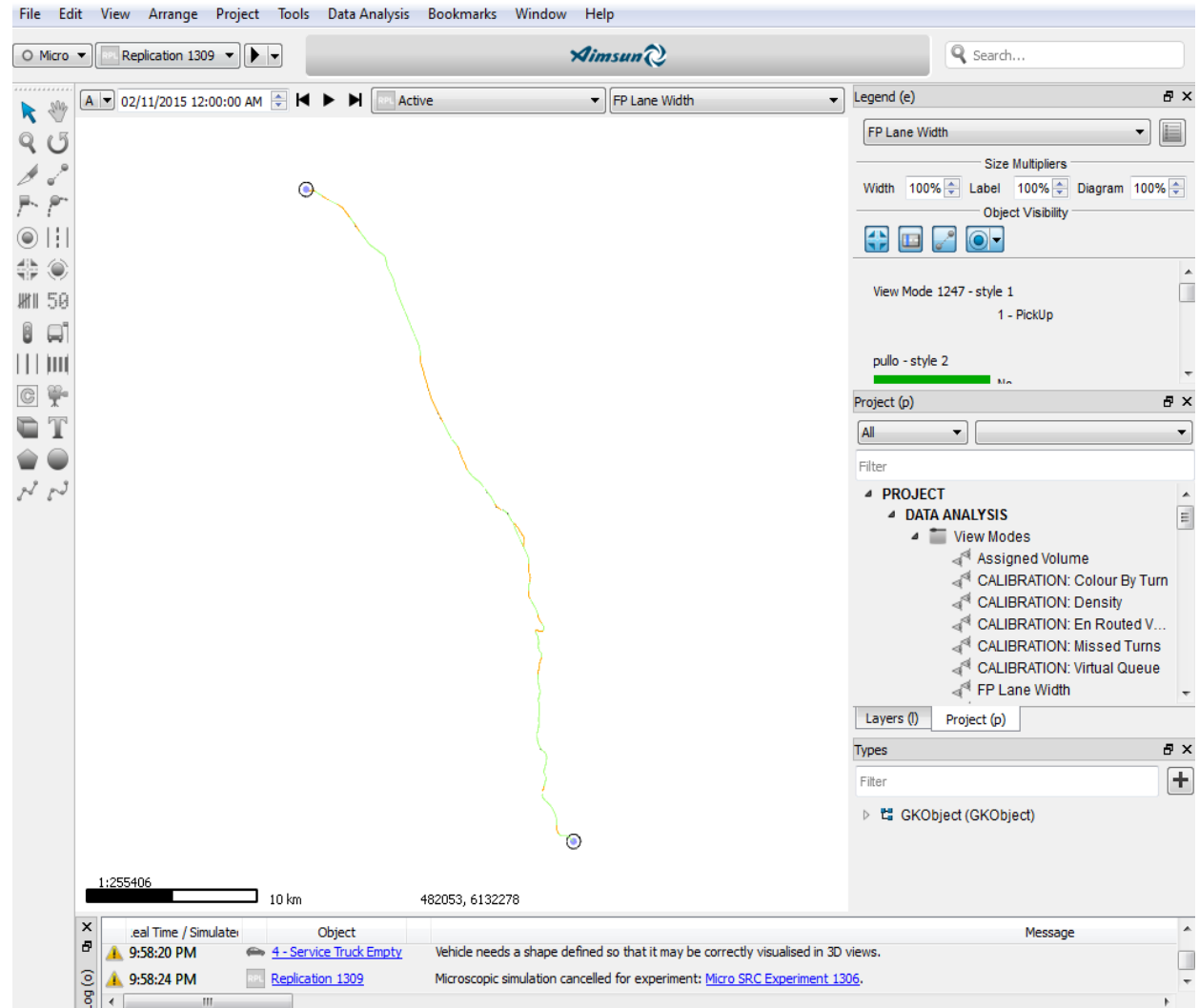
 Aimsun scripts to
automate building
models



Calibrate simulation



Make change and
generate output
metrics of interest



Microsimulation: entire workflow

Traffic data and
Field mapping



Cleaning/preparing
all data



Aimsun scripts to
automate building
models



Calibrate simulation



Make change and
generate output
metrics of interest

Main input:

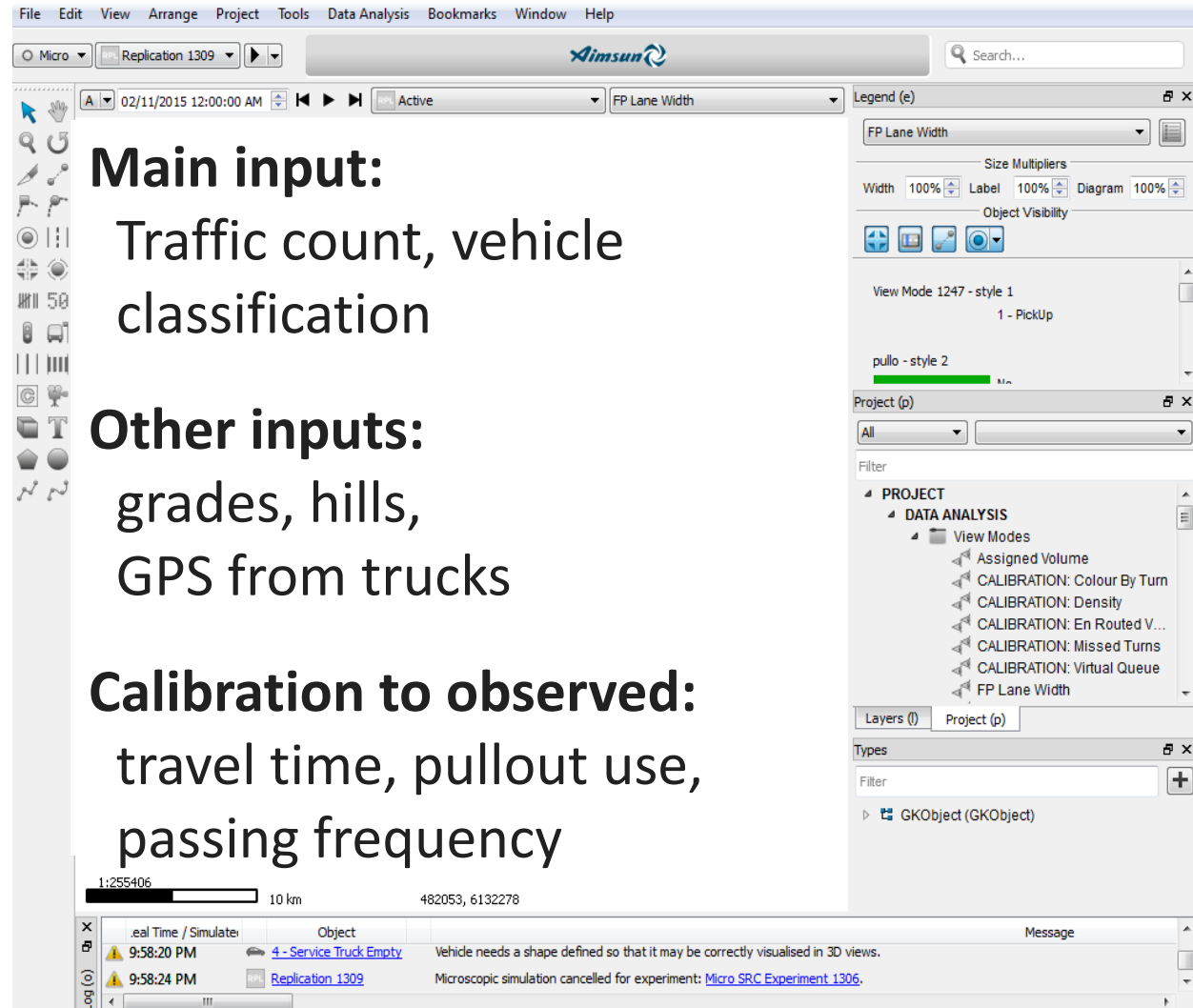
Traffic count, vehicle
classification

Other inputs:

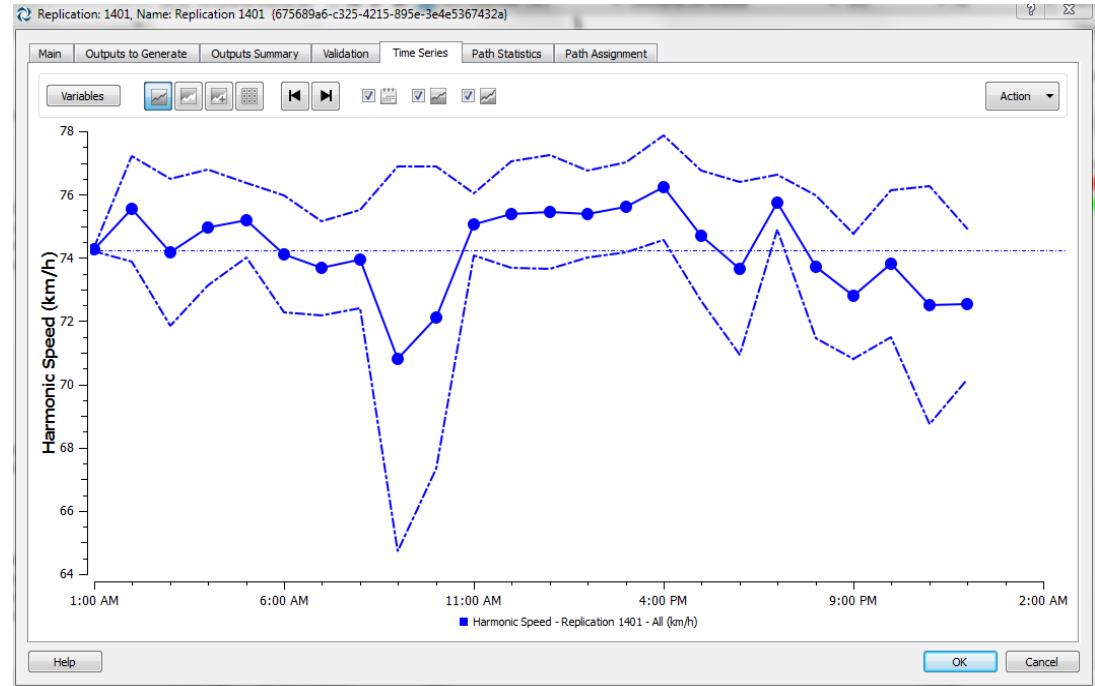
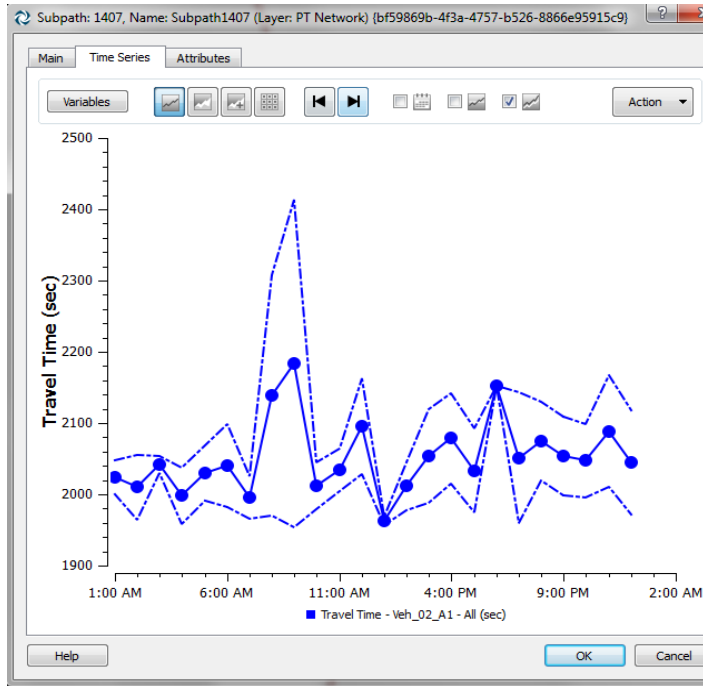
grades, hills,
GPS from trucks

Calibration to observed:

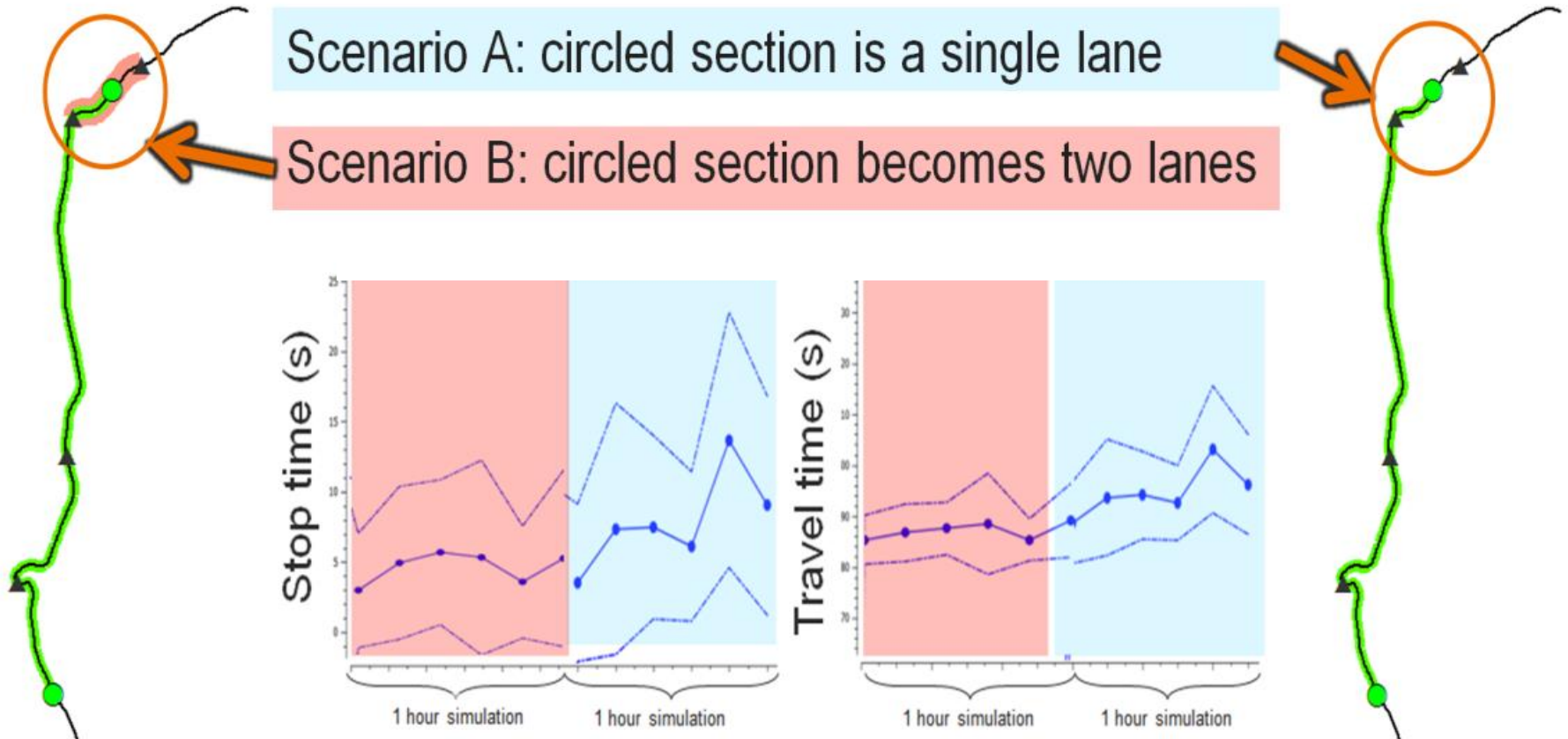
travel time, pullout use,
passing frequency



Microsimulation: output examples



Microsimulation: output examples



Microsimulation: qualitative aspects

Workshops: key safety traffic metrics (MOE)

- Percent time spent following
- Average/proportion of time in pullouts
- Number of pullout overcrowding occurrences

LOS: what are the thresholds for

BAD, **OK**, **GOOD** for each MOE?

Conclusions: benefits

Analysis of field data only

- Speed profiles of different vehicle types
- Improving road asset database (widths, pullouts, etc)
- Confirmation of users (road use agreements)

Using field data to drive traffic microsimulation

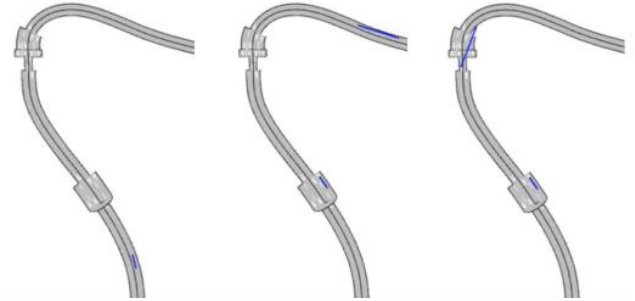
- Test effects of different scheduling
- Test effect of road improvements
- Test effects of increased traffic volumes

Safety	Finance
X	
X	X
	X
X	X
X	X
X	X

Conclusions: future

Work this year in BC

- Florence calibration in progress: UBC; methodology being finalized
- Bamfield study now has all field work done
 - Video post-processing will be tested
 - Calibration to follow – with passing
 - Looking at detailed vehicle classification



Further in the future...

- The API tool will work for anyone with an Aimsun license
 - Does not yet support platoons.. future?
- Video post-processing – lots could be done.. future?
- Motion cameras – keep eye on..
- Comparing traffic metrics between study locations may yield interesting results

Cooperators

This year we are working closely with UBC in building simulations on Bamfield road with the help of Island Timberlands



BC FLNRO

NR Canada

Aimsun

UBC – Radio Science Lab

Island Timberlands

FPIinnovations:

Al Bradley

Dawson Markle

Mithun Shetty

Glen Legere

Blane Grann



Thank you! Questions?



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